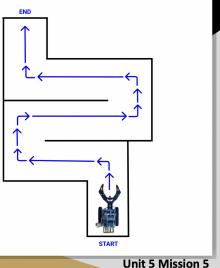
Activity 1: Planning out the Maze

For this mission, the challenge is to complete a maze using code. We can break down the mission into tasks:

- What specific movements are needed to complete the maze?
- How can we measure the Ultimate's movements?
- How will we convert these measurements into executable code?

We'll discover how to solve these problems in the following activities.

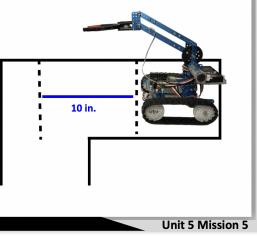


Activity 2: Measuring Distances

To begin, measure the forward distances on your map using a ruler and turns using a protractor. **N Record** the measurements necessary for maze completion in your notebook.

Try using pseudocode. Pseudocode is a way to describe the steps in a program using simple wording. For example:

- 1. Move forward <u>10</u> in
- 2. Turn left <u>90</u> degrees
- 3. Move forward 14 in
- 4. Turn right <u>45</u> degrees



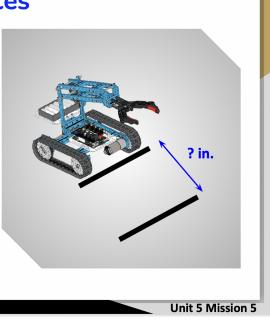
Activity 2: Measuring Distances

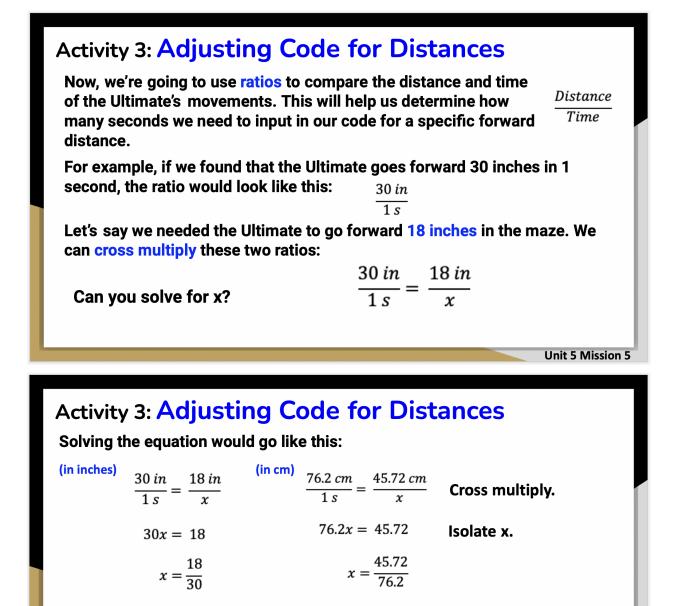
Next, investigate how far the Ultimate travels when moving forward at 50% for 1 second.

<u>Note</u>: Measurements may change over time depending on battery charge.

How much time it will take for the Ultimate to turn right/left the amount you need?

Experiment with different time frames and record.





x = 0.6 seconds

Lastly, input the time duration into the code: 2 move forward at power 50 % for 0.6 secs

x = 0.6 seconds

Unit 5 Mission 5



Enjoying the Curriculum Overview?

Purchase our Full Curriculum at <u>ExploringRobotics.com</u>